

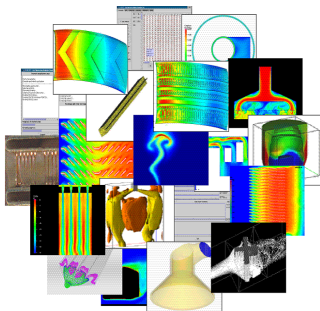
Open-source CFD software: FEATFLOW

The FEA(S)T groups

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Lake Tahoe, January 7, 2009

- 1 FeatFlow
 - FeatFlow 1.x
 - FeatFlow 2.0
- 2 Preprocessing
 - DeVISO Grid3D
- 3 Example application
 - Poisson equation
- 4 Postprocessing
 - General Mesh Viewer
- 5 UnConventional HPC
 - FEAST



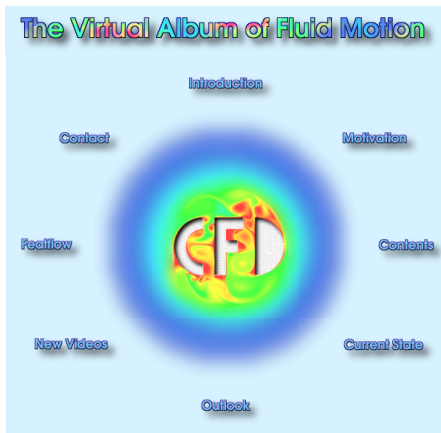
Finite Element Analysis Toolbox + Flow solver

High performance unstructured finite element package for the numerical solution of the incompressible Navier-Stokes equations

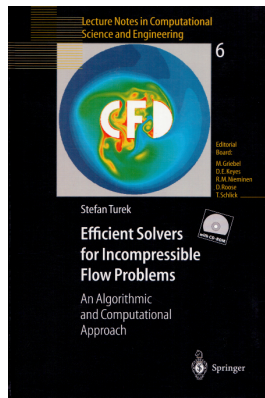
- based on the finite element packages FEAT2D and FEAT3D
- written in Fortran 77 (and some C routines) by Stefan Turek
- designed for education, scientific research and industrial applications
- full source-code and user manuals are available online
- many extensions are not included in the official release 😞

Visit the FEATFLOW homepage

<http://www.featflow.de>



<http://www.featflow.de/album>



Theoretical background

Incompressible Navier-Stokes equations

$$\mathbf{u}_t - \nu \Delta \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} + \nabla p = \mathbf{f}, \quad \nabla \cdot \mathbf{u} = 0, \quad \text{in } \Omega \times (0, T]$$

- Spatial discretization techniques
 - nonconforming rotated multilinear finite elements for \mathbf{u}
 - piecewise constant pressure approximation for p
 - Samarskij upwind or streamline diffusion stabilization
- Temporal discretization techniques
 - implicit one-step- θ -scheme (Backward Euler, Crank-Nicolson)
 - implicit fractional-step- θ scheme (second-order accurate)
 - adaptive time-stepping based on local discretization error

Discretized incompressible Navier-Stokes equations

Given \mathbf{u}^n , \mathbf{g} and k , solve for $\mathbf{u} = \mathbf{u}^{n+1}$ and $p = p^{n+1}$

$$[M + \theta k N(\mathbf{u})]\mathbf{u} + kBp = \mathbf{g}, \quad B^T \mathbf{u} = 0$$

where $\mathbf{g} = [M - \theta_1 k N(\mathbf{u}^n)]\mathbf{u}^n + \theta_2 k \mathbf{f}^{n+1} + \theta_3 k \mathbf{f}^n$

- Nonlinear/linear solution strategies
 - coupled fixed point defect correction method CC2D/CC3D
 - nonlinear discrete projection scheme PP2D/PP3D
 - linear multigrid techniques with adaptive step-length control
 - ILU/SOR or Vanka-like block Gauß-Seidel smoother/solver

Finite Element Analysis Toolbox + Flow solver

The modern successor of FEATFLOW 1.x for the numerical solution of **flow problems** by the finite element method

- modular object-oriented design by Michael Köster et al.
- written in Fortran 95 (kernel + applications)
- external libraries in F77/C (BLAS, UMFPACK, LAPACK)
- designed for education of students and scientific research
- detailed in-place documentation of the source-code

Official release not yet available; get the ALPHA snapshot

http://www.featflow.de/download/Featflow2_2.0ALPHA.tar.gz

Unix/Linux and Mac OS X

- compatible C and Fortran compiler
 - GCC and G95 **version 0.91**
 - Intel[®] C++/Fortran Compilers for Linux
 - Sun Studio C, C++ and Fortran Compilers
- GNU make utility
 - Makefiles are provided for all applications

Windows XP, Vista

- Microsoft[®] VisualStudio 2003, 2005 or 2008
 - Project files are provided for all applications
- Intel[®] C++/Fortran Compilers for Windows
- Cygwin[™] environment
 - General Mesh Viewer (GMV)

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 - General Mesh Viewer (GMV)

Linux is used for this workshop

- Unpack the downloaded archive file

```
$ tar xvzf Featflow2_2.0ALPHA.tar.gz
```

- Change into the base directory

```
$ cd Featflow2 ; ls
```

```
applications    Globals.power    object
bin              Globals.sparc    readme.txt
codefragments   Globals.x86      Rules_apps_f90.mk
feat2win.txt     Globals.x86_64   Rules_apps.mk
Globals.alpha    kernel           Rules_libs.mk
Globals.ia64     libraries        VERSIONS
Globals.mac      Makefile
Globals.mk       matlab
```

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```

Top-level build options

```
$ make [ALT=xxx] [ID=yyy] <target>
```

- Some values for target

- help - print additional help and further option
- id - print out settings for current ID
- all - compile all libraries and application modules
- apps - compile all application modules
- libs - compile all libraries

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- help - print additional help and further option
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- Some available make modifiers

- ALT=xxx - specify alternative ID-xxx to use
 - ID=yyy - override the autodetected architecture ID by yyy

Understanding the ALT/ID concept

```
$ make id
```

run on x86_64 GNU/Linux

```
Machine-ID (Barracuda) : pc64-core2-linux
```

```
Compilers to be used:
```

```
C compiler:      /usr/bin/gcc
C++ compiler:    /usr/bin/g++
Fortran compiler: /usr/local/g95/32bit_integers/0.91/bin/g95
F-Library archiver: /usr/bin/ar
C-Library archiver: /usr/bin/ar
```

```
Flags to be used:
```

```
OPTFLAGS      = -O3 -m64 -ffast-math -fexpensive-optimizations -fprefetch-loop-arrays -mmmx -msse -msse2 -msse3
OPTFLAGSC     =
OPTFLAGSCPP   =
OPTFLAGSF     =
OPTFLAGSDDEBUG = -g
OPTFLAGSCDDEBUG =
OPTFLAGSCPPDDEBUG=
OPTFLAGSFDEBUG = -O0 -g -Wall -fbounds-check -ftrace=full
FCFLAGS       = -pipe -fmod= -march=nocona
CCFLAGS       = -pipe -march=nocona
CPPFLAGS      = -pipe -march=nocona
BUILDLIB      = feat3d feat2d sysutils umfpack2 amd umfpack4 minisplib lapack blas
BLASLIB       = (standard BLAS, included in installation package)
LAPACKLIB     = (standard LAPACK, included in installation package)
LDLIBS        =
LDLFLAGS      =
```

Understanding the ALT/ID concept

```
$ make ID=pc-core2-linux id
```

run on x86_64 GNU/Linux

```
Machine-ID (Barracuda) : pc-core2-linux
```

```
Compilers to be used:
```

```
C compiler:      /usr/bin/gcc
C++ compiler:   /usr/bin/g++
Fortran compiler: /usr/local/g95/32bit_integers/0.91/bin/g95
F-Library archiver: /usr/bin/ar
C-Library archiver: /usr/bin/ar
```

```
Flags to be used:
```

```
OPTFLAGS      = -O3 -m32 -ffast-math -fexpensive-optimizations -fprefetch-loop-arrays -mmmx -msse -msse2 -msse3
OPTFLAGSC     =
OPTFLAGSCPP   =
OPTFLAGSF     =
OPTFLAGSDDEBUG = -g
OPTFLAGSCDDEBUG =
OPTFLAGSCPPDDEBUG=
OPTFLAGSFDEBUG = -O0 -g -Wall -fbounds-check -ftrace=full
FCFLAGS       = -pipe -fmod= -march=nocona
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BLASLIB       = (standard BLAS, included in installation package)
LAPACKLIB     = (standard LAPACK, included in installation package)
LDLIBS        =
LDLFLAGS      =
```


Understanding the ALT/ID concept

```
$ make ALT=ifc id
```

run on x86_64 GNU/Linux

Machine-ID (Barracuda) : pc64-core2-linux-ifc

Compilers to be used:

```
C compiler:      /usr/local/intel/cce/10.1.021/bin/icc
C++ compiler:   /usr/local/intel/cce/10.1.021/bin/icpc
Fortran compiler: /usr/local/intel/fce/10.1.021/bin/ifort
F-Library archiver: /usr/local/intel/fce/10.1.021/bin/xiar
C-Library archiver: /usr/local/intel/fce/10.1.021/bin/xiar
```

Flags to be used:

```
OPTFLAGS      = -O3 -ipo -xT
OPTFLAGSC     =
OPTFLAGSCPP   =
OPTFLAGSF     =
OPTFLAGSDDEBUG = -g
OPTFLAGSCDEBUG = -traceback
OPTFLAGSCPPDEBUG = -traceback
OPTFLAGSFDEBUG = -warn all -check all -traceback
FCFLAGS      = -cm -fpe0 -vec-report0 -module
CFLAGS       = -vec-report0
CPPFLAGS     = -vec-report0
BUILDLIB     = feat3d feat2d sysutils umpack2 amd umpack4 minisplib lapack blas
BLASLIB      = (standard BLAS, included in installation package)
LAPACKLIB    = (standard LAPACK, included in installation package)
LDLIBS       =
LDLFLAGS     = -lsvml
```

Understanding the ALT/ID concept

```
$ make [ALT=xxx] [ID=yyy] <target>
```

- compiler settings are defined in the global configuration files
Global. [alpha, ia64, mac, power, sparc, x86, x86_64]
- new compilers and/or architectures can be easily included
- special purpose settings, e.g. pc64-opteron-linux-ifclarge

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Building the Poisson example application

```
$ cd applications/poisson
```

```
$ make
```

... after some time ...

Done, poisson-pc64-core2-linux is ready.

Understanding the ALT/ID concept

```
$ make [ALT=xxx] [ID=yyy] <target>
```

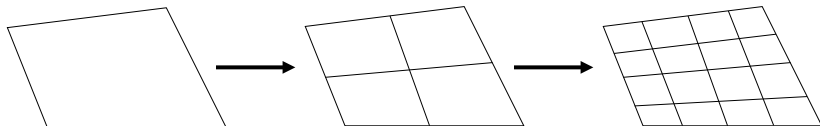
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Building the Poisson example application

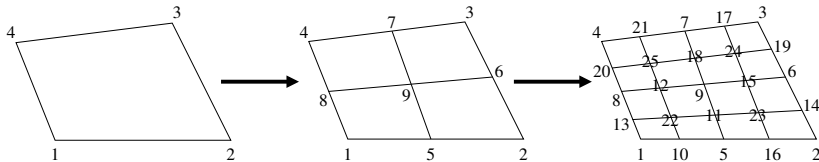
```
$ cd applications/poisson  
$ make debug          turn on debugging facilities of the compiler  
... after some time ...  
Done, poisson-pc64-core2-linux is ready.
```

Preprocessing: *Grid generation*

- 1 Construct initial coarse grid in the external preprocessing step
- 2 Generate hierarchy of regularly refined meshes in the application



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- 2 Generate hierarchy of regularly refined meshes in the application



Two-level ordering strategy

- adopt all coordinates from coarser grid levels unchanged
- introduce new coordinates at edge/face/cell midpoints

- File format is described in the FEAT2D/FEAT3D manuals
- Supported element types: triangles, quads (2D) and hexahedra (3D)

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- Domain triangulation is specified in TRI file (2D/3D)
 - coordinate values of vertices in the interior
 - parameter values of vertices at the boundary
 - elements in terms of their corner nodes
 - first two lines are treated as header/comments!

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- Supported element types: triangles, quads (2D) and hexahedra (3D)
- Domain triangulation is specified in TRI file (2D/3D)
 - coordinate values of vertices in the interior
 - parameter values of vertices at the boundary
 - elements in terms of their corner nodes
 - first two lines are treated as header/comments!
- Boundary parametrization is specified in PRM file (only 2D)
 - each boundary component is described by $p \in [0, p_{\max}]$
 - the 'interior' is located left to the boundary
 - do not mix up (counter-)clockwise orientation
 - supported boundary types: lines, (arcs of) circles

Coarse grid generator for FEATFLOW and FEAST

- written in Java + OpenGL and published under the GPL
- available at <http://www.feast.uni-dortmund.de>
- send requests, bug reports to devisor@featflow.de
- on-line help system and self-contained tutorial included

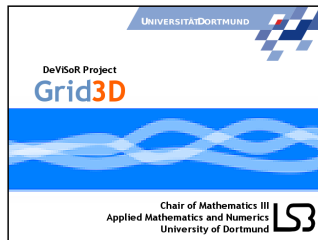
- Unpack the downloaded archive file

```
$ unzip grid-3.0.21.zip
```

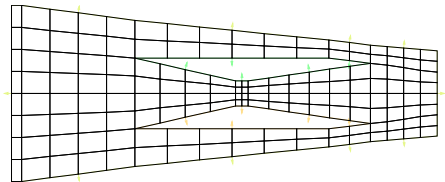
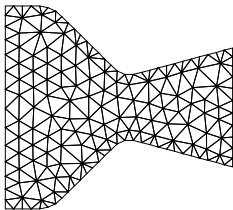
- Start the application

```
$ cd grid-3.0.21
```

```
$ java -jar grid3d.jar
```



- GiD – the personal pre- and post-processor
 - evaluation version is available at <http://gid.cimne.upc.es>
 - fully automatic structured and unstructured coarse grid generator
 - supports triangular, quadrilateral, tetrahedral, hexahedral elements
 - provides an effective easy-to-use and geometric user interface
- GiD2Feat – set of tools to convert GiD meshes to PRM/TRI files



Example application: *Poisson equation*

- Change into the application source directory

```
$ cd applications/poisson/src; ls  
  
    poissonXd_callback.f90  poisson.f90  
    poissonXd_methodYYY.f90
```

- Open the application main source file

```
$ emacs poisson.f90
```

- Change into the application source directory

```
$ cd applications/poisson/src; ls  
  
poissonXd_callback.f90  poisson.f90  
poissonXd_methodYYY.f90
```

- Open the application main source file

```
$ emacs poisson.f90
```

Initialization and finalization

- `system_init()` initialize system-wide settings
- `storage_init(999, 100)` initialize storage management
- `storage_done()` finalize storage management

Sample problem: $-\Delta u = f$ in $\Omega = (0,1)^2$, $u = 0$ on $\partial\Omega$

■ right hand side $f(x,y) = 32(x(1-x) + y(1-y))$

■ analytical solution $u(x,y) = 16x(1-x)y(1-y)$

■ Open the demonstration module file

```
$ emacs poisson2d_method0_simple.f90
```

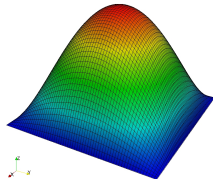
■ contains the corresponding subroutine

■ includes all required kernel modules

■ provides detailed step-by-step tutorial

■ Open the callback function module file

```
$ emacs poisson2d_callback.f90
```



Grid generation

- `boundary_read_prm` read boundary parametrization
- `tria_readTriFile2D` read domain triangulation
- `tria_quickRefine2LevelOrdering` perform regular refinement
- `tria_initStandardMeshFromRaw` generate data structures

Spatial discretization

- `spdiscr_initBlockDiscr2D` prepare block discretization
- `spdiscr_initDiscr_simple` initialize spatial discretization
- `bilf_createMatrixStructure` create scalar matrix structure
- `bilf_buildMatrixScalar` discretize the bilinear form
- `linf_buildVectorScalar` discretize the linear form/r.h.s.

Dirichlet boundary conditions

- `boundary_createRegion` specify boundary segment
- `bcasm_newDirichletBConRealBD` calculate discrete b.c.'s
- `matfil_discreteBC` set b.c.'s in system matrix
- `vecfil_discreteBCrhs` set b.c.'s in right hand side
- `vecfil_discreteBCsol` set b.c.'s in solution vector

Linear BiCGStab solver

- `linsol_initBiCGStab` initialize linear solver
- `linsol_setMatrices` attach system matrix
- `linsol_initStructure, linsol_initData`
- `linsol_solveAdaptively` solve linear system

Solution output

- `ucd_startGMV` start export on GMV format
- `ucd_addVariableVertexBased` add vertex-based solution data
- `ucd_addVariableElementBased` add cell-based solution data
- `ucd_write` write solution data to file

Clean-up and finalization

- `XXX_release`, `XXX_releaseYYY` free allocated memory
- `XXX_done` stop sub-system

General naming convention of subroutines

- `abbreviatedModulefile_NameOfSubroutine`

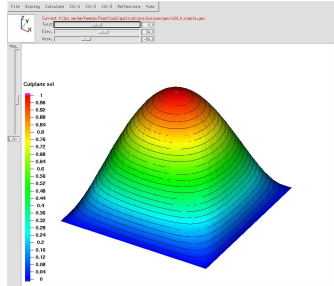
Postprocessing: *Visualization of the solution*

3D scientific visualization tool

- developed at Los Alamos National Lab by Frank Ortega
- available at <http://www-xdiv.lanl.gov/XCM/gmv/>
- supported OS: UNIX/Linux, Mac OS X, Windows (Cygwin)

- unstructured meshes in 2D/3D
- cutlines, cutplanes, cutspheres
- vertex-based, cell-based data sets
- contour, vector plots

Alternative: importer for ParaView based on development CVS-version

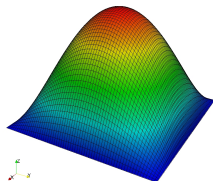


Advanced topics: *Multigrid, Mesh Adaptation, ...*

Sample problem: $-\Delta u = f$ in $\Omega = (0,1)^2$, $u = 0$ on $\partial\Omega$

- right hand side $f(x, y) = 32(x(1-x) + y(1-y))$
- analytical solution $u(x, y) = 16x(1-x)y(1-y)$

- Open the demonstration module file
\$ emacs poisson2d_method1_mg.f90
 - linear geometric multigrid solver
 - Jacobi or ILU(0) smoother
 - direct coarse grid solver (UMFPACK)

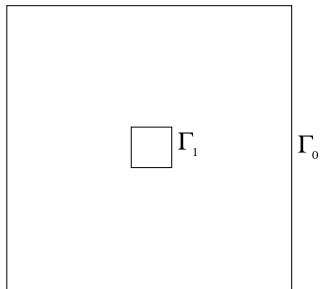


Example: applications/anisotropicdiffusion.f90

$$\mathcal{D} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} k_1 & 0 \\ 0 & k_2 \end{pmatrix} \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$

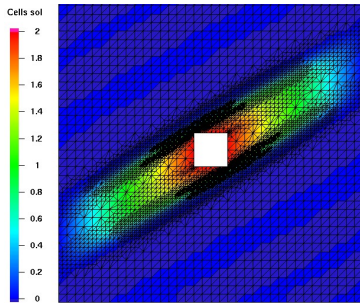
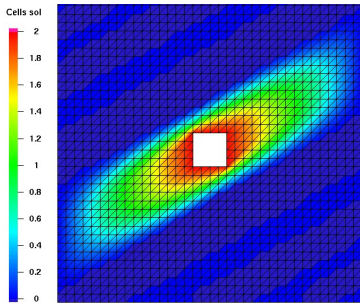
$$\begin{cases} -\nabla \cdot (\mathcal{D}\nabla u) = 0 & \text{in } \Omega \\ u = 0 & \text{on } \Gamma_0 \\ u = 2 & \text{on } \Gamma_1 \end{cases}$$

- $k_1 = 100, \quad k_2 = 1, \quad \theta = -\frac{\pi}{6}$
- linear finite elements, $h = 1/36$
- Galerkin fails: $u^{\min} = -0.0553$
- h -adaptation: $u^{\min} = -0.0068$



Example: applications/anisotropicdiffusion.f90

$$\mathcal{D} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} k_1 & 0 \\ 0 & k_2 \end{pmatrix} \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$



- conformal mesh refinement based on red-green strategy
- vertex-locking algorithm for mesh re-coarsening procedure
- nodal generation function stores birth certificates
 - provides complete characterization of elements
 - youngest node corresponds to refinement level
 - is required for the vertex-locking algorithm
- state function for element characterization
- local two-level ordering strategy

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This has been addressed in the talk on Monday

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Triangulation $\mathcal{T}_m(\mathcal{E}_m, \mathcal{V}_m)$, $m = 0, 1, 2, \dots$ consists of

$$\mathcal{E}_m = \{\Omega_k : k = 1, \dots, N_E\} \quad \text{and} \quad \mathcal{V}_m = \{v_i : i = 1, \dots, N_V\}$$

- nodal **generation function** $g : \mathcal{V}_m \rightarrow \mathbb{N}_0$ is defined recursively

$$g(v_i) := \begin{cases} 0 & \text{if } v_i \in \mathcal{V}_0 \\ \max_{v_j \in \Gamma_{kl}} g(v_j) + 1 & \text{if } v_i \in \Gamma_{kl} := \bar{\Omega}_k \cap \bar{\Omega}_l \\ \max_{v_j \in \partial\Omega_k} g(v_j) + 1 & \text{if } v_i \in \Omega_k \setminus \partial\Omega_k \end{cases}$$

Idea I: State function $s : \mathcal{E}_m \rightarrow \mathbb{Z}$ (in MSB representation)

- Set Bit [0] to 1 for quadrilateral, otherwise set it to zero
- Set Bit [k=1..4] to 1 if both endpoints of edge k have same age
- If no two endpoints have same age, then find local position k of the youngest vertex, set Bit [k] to 1 and negate the state

Idea II: Define **local ordering strategy** within each element *a priori*

element characterization	element state
triangle/quadrilateral from \mathcal{T}_0	0/1
green quadrilateral	3, 5, 9, 11,17, 21
red quadrilateral	7, 13, 19, 25
inner red triangle	14
'other' triangle	2, 4, 8
green triangle	-8, -4, -2

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Idea II: Define **local ordering strategy** within each element *a priori*

element characterization	element state
triangle/quadrilateral from \mathcal{T}_0	0/1
green quadrilateral	3, 5, 9, 11,17, 21
red quadrilateral	7, 13, 19, 25
inner red triangle	14
'other' triangle	2, 4, 8
green triangle	-8, -4, -2

Idea I: State function $s : \mathcal{E}_m \rightarrow \mathbb{Z}$ (in MSB representation)

- Set Bit [0] to 1 for quadrilateral, otherwise set it to zero
- Set Bit [k=1..4] to 1 if both endpoints of edge k have same age
- If no two endpoints have same age, then find local position k of the youngest vertex, set Bit [k] to 1 and negate the state

Idea II: Define **local ordering strategy** within each element *a priori*

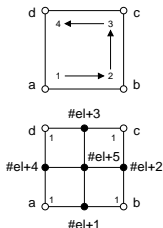
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triangle/quadrilateral from \mathcal{T}_0	0/1
green quadrilateral	5, 21
red quadrilateral	13
inner red triangle	14
'other' triangle	4
green triangle	-8, -4, -2



Concept of dynamically allocatable arrays in Fortran 9x

- integer, dimension(:), allocatable :: Iarray
- allocate(Iarray(n)) allocate array of size n dynamically
- deallocate(Iarray) deallocate dynamically allocated array

Concept of dynamically allocatable arrays in Fortran 9x

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Concept of dynamically allocatable arrays in FeatFlow

- `storage_init, storage_done` initialize/finalize storage
- `storage_new` allocate new memory storage
- `storage_realloc` re-allocate memory storage
- `storage_free` deallocate memory storage
- `storage_getbase_XXX` access memory storage

- Supported data: 8/16/32/64 integer, SP/DP real, logical, strings
- Memory storage is accessible via integer handle `ihandle`
- Pointer to the memory is assigned via `storage_getbase_XXX`

Implementation details

- memory storage handling is internally mapped to `de/allocate`
- different storage management can be implemented without changes
- handles can be easily passed to subroutines and functions
- derived types typically consist of a set of handles + scalar data

Derived type for triangulation structure

```
type t_triangulation
  integer :: ndim = 0
  integer :: NVT = 0
  integer :: NMT = 0
  integer :: NAT = 0
  integer :: NEL = 0
  . . .
  integer :: h_DvertexCoords = ST_NOHANDLE
  integer :: h_IverticesAtElement = ST_NOHANDLE
  integer :: h_IneighboursAtElement = ST_NOHANDLE
end type
```

Impl

ges

Create new storage

- `storage_new (scall, sname, Isize, ctype, ihandle, &cinitNewBlock, <rheap>)`
- `ctype` \in {`ST_DOUBLE`,`ST_SINGLE`,`ST_INTx`,`ST_CHAR`,`ST_LOGICAL`}
- `cinitNewBlock` \in {`ST_NEWBLOCK_ZERO`,`ST_NEWBLOCK_NOINIT`}

Accessing storage, e.g. 2-dimensional double array

- `real(DP)`, `dimension(:, :)`, `pointer :: p_Darray`
- `storage_getbase_double2D (ihandle, p_Darray, <rheap>)`

Releasing storage

- `storage_free (ihandle)`

UnConventional High Performance Computing

Finite Element Analysis & Solution Tools

High performance finite element package for the efficient simulation of large scale problems on heterogeneous hardware

- written in Fortran 90 and C (MPI communication)
- CFD (Stokes, Navier-Stokes), CSM (Elasticity)
- macro-wise domain decomposition approach
- fast and robust parallel multigrid methods
- unconventional hardware as FEM co-processors

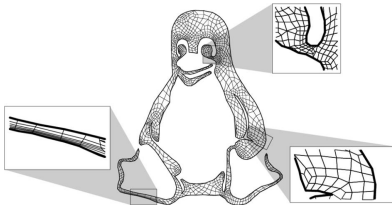
Visit the FEAST homepage

<http://www.feast.uni-dortmund.de>

Scalable Recursive Clustering (ScaRC) solver

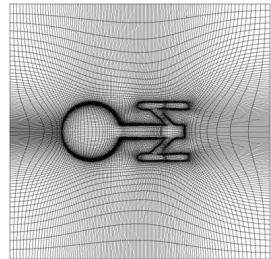
Combine domain decomposition and cascaded multigrid methods

Globally unstructured



hide anisotropies to improve robustness

Locally structured





- Graphic processing unit (GPU)
128 parallel scalar processors
@ 1.35 GHz, ≈ 350 GFLOP/s
GDDR3 memory @ 900 MHz

- Cell multi-core processor (PS3)
7 synergistic processing units
@ 3.2 GHz, **218 GFLOPS/s**
Memory @ 3.2 GHz



Unified FEAT+FEAST finite element package

- Decompose the domain into **globally** unstructured macro-cells
- Use generalized tensor product grid or unstructured mesh **locally**
- Reuse FEM co-processors in the FEATFLOW package
- Enable special features, (e.g. *h*-adaptation) per macro-cell

On-line resources and additional material

- FeatFlow project: <http://www.featflow.de>
- Feast project: <http://www.feast.uni-dortmund.de>