## DELFT UNIVERSITY OF TECHNOLOGY



FACULTY OF ELECTRICAL ENGINEERING, MATHEMATICS AND COMPUTER SCIENCE

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## TEST NUMERICAL METHODS FOR DIFFERENTIAL EQUATIONS (WI3097TU WI3097Minor WI3197Minor AESB2210 AESB2210-18 CTB2400 ) Thursday July 4th 2019, 13:30-16:30

**Number of questions:** This is an exam with 12 open questions, subdivided in 3 main questions.

**Answers** All answers require arguments and/or shown calculation steps. Answers without arguments or calculation steps will not give points.

**Tools** Only a non-graphical, non-programmable calculator is permitted. All other electronic tools are not permitted.

**Assessment** In total 20 points can be earned. The final not-rounded grade is given by P/2, where P is the number of points earned.

1. For the initial value problem y' = f(t, y),  $y(t_0) = y_0$ , we use the following integration method:

$$\begin{cases} w_{n+1}^* = w_n + \Delta t f(t_n, w_n) \\ w_{n+1} = w_n + \frac{\Delta t}{2} \left( f(t_n, w_n) + f(t_{n+1}, w_{n+1}^*) \right). \end{cases}$$
 (1)

Here  $\Delta t$  denotes the timestep and  $w_n$  represents the numerical approximation at time  $t_n$ .

(a) Show that the local truncation error of the integration method is of the order  $\mathcal{O}(\Delta t^2)$ . (You are not allowed to use the test equation here.) (3pt.)

Consider the following initial value problem

$$\begin{cases} \frac{d^2y}{dt^2} + 4y = \cos t, \\ y(0) = 1, \quad \frac{dy}{dt}(0) = 0. \end{cases}$$
 (2)

(b) Show that the above initial value problem can be written as

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}' = \begin{pmatrix} 0 & 1 \\ -4 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 0 \\ \cos t \end{pmatrix}.$$
 (3)

Give the initial conditions for  $x_1(0)$  and  $x_2(0)$  as well. (1pt.)

- (c) Calculate one step with integration method (1), in which  $\Delta t = 0.1$  and  $t_0 = 0$ , applied to (3) and use the given initial conditions. (2pt.)
- (d) Derive the amplification factor for the integration method. (2pt.)
- (e) Examine for which stepsizes  $\Delta t$ , the integration method (1), applied to the initial value problem (3), is stable. (2pt.)

2. We want to find an approximation of the zero p of a function f, i.e. we want to find p such that f(p) = 0. However, we do not known the function f, but only some values of f in some points x are known, which are given in the table to the right.

x	f(x)
1	-1
4/3	-2/9
7/5	-1/25
10/7	2/49
2	2

Therefore we consider using the Secant method:

$$p_n = p_{n-1} - \frac{f(p_{n-1})}{K_{n-1}},\tag{4}$$

with  $K_{n-1}$  an approximation to  $f'(p_{n-1})$ , and in which  $p_{n-2}$ ,  $p_{n-1}$  and  $p_n$  are three consecutive approximations of the zero p.

Equation (4) is based on formulating the linear interpolating polynomial L of f based on  $p_0$  and  $p_1$ :

$$L(x) = f(p_0) + \frac{f(p_1) - f(p_0)}{p_1 - p_0} (x - p_0),$$

after which  $p_2$  is found by solving  $L(p_2) = 0$  for  $p_2$ .

(a) Show that, for n = 2,  $K_1$  is given by

$$K_1 = \frac{f(p_1) - f(p_0)}{p_1 - p_0},$$

by solving  $L(p_2) = 0$  for  $p_2$ .

(2 pt.)

(11/2 pt.)

(1 pt.)

- (b) Take  $p_0 = 1$  and  $p_1 = 2$ . Approximate the zero p of f by calculating  $p_2$ . You may round  $p_2$  to a value of x as given in the table. (1 pt.)
- (c) Repeat the above steps with n = 3 by stating the formula for  $K_2$  and calculating  $p_3$ . You may round  $p_3$  to a value of x as given in the table. (2 pt.)
- 3. We are interested in the numerical integration of the integral

$$\int_0^{2\pi} y(x)dx,$$

with  $y(x) = 1 + \sin(x)$ .

- (a) Approximate the above integral with the right composite Rectangle rule using  $h = \pi/2$ . (1½ pt.)
- (b) Approximate the above integral with the composite Trapezoidal rule using  $h = \pi/2$ . (1 pt
- (c) The magnitude of the errors  $\varepsilon_R$  and  $\varepsilon_T$  of the approximations are bounded by

$$\varepsilon_R \le \pi h \max_{x \in [0, 2\pi]} |y'(x)|,$$

for the right composite Rectangle rule and by

$$\varepsilon_T \le \frac{\pi}{6} h^2 \max_{x \in [0, 2\pi]} |y''(x)|,$$

for the composite Trapezoidal rule. Give explicit upper bounds for both rules for general values of h.

(d) Select and motivate which method you prefer if h becomes small.

## For the answers of this test we refer to: